

PROBLEM SET #04- ANSWER KEY

FIRST LIN ALGEBRA PROBLEM SET

(1) Simon & Blume question 10.5 (page 208).

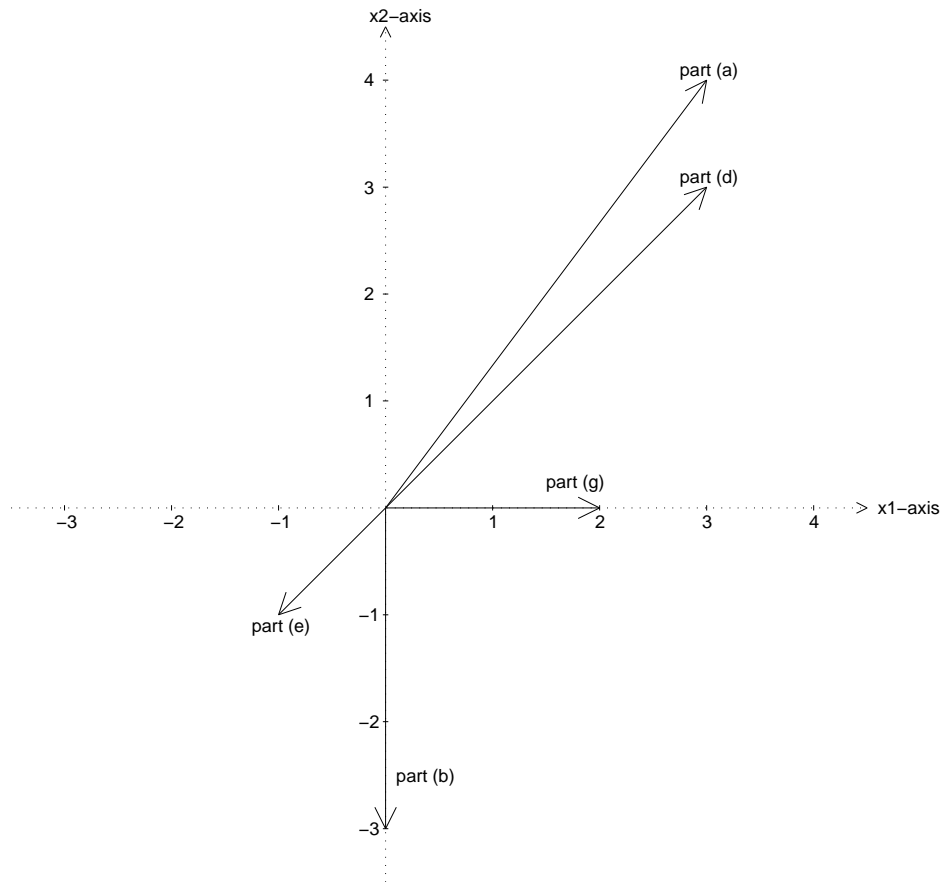
Ans: Let $\mathbf{u} = (1,2)$, $\mathbf{v} = (0,1)$, $\mathbf{w} = (1,-3)$, $\mathbf{x} = (1,2,0)$ and $\mathbf{z} = (0,1,1)$

- (i) $\mathbf{u} + \mathbf{v} = (1,2) + (0,1) = (1,3)$.
- (ii) $-4\mathbf{w} = -4(1,-3) = (-4,12)$.
- (iii) $\mathbf{u} + \mathbf{z}$ is not defined as \mathbf{u} is an (1×2) vector and \mathbf{z} is an (1×3) vector.
- (iv) $3\mathbf{z} = 3(0,1,1) = (0,3,3)$.
- (v) $2\mathbf{v} = 2(0,1) = (0,2)$.
- (vi) $\mathbf{u} + 2\mathbf{v} = (1,2) + 2(0,1) = (1,4)$.
- (vii) $\mathbf{u} - \mathbf{v} = (1,2) - (0,1) = (1,1)$.
- (viii) $3\mathbf{x} + \mathbf{z} = 3(1,2,0) + (0,1,1) = (3,7,1)$.
- (ix) $-2\mathbf{x} = -2(1,2,0) = (-2,-4,0)$.
- (x) $\mathbf{w} + 2\mathbf{x}$ is not defined as \mathbf{w} is an (1×2) vector and \mathbf{x} is an (1×3) vector

(2) Simon & Blume question 10.10 (page 220)

Ans: The vectors for part a,b,d,e, and g are displayed in figure 1. The vectors for part c and f are displayed in figure 2.

FIGURE 1. The vectors for part a,b,d,e, and g



- a) $\|(3, 4)\| = \sqrt{3^2 + 4^2} = \sqrt{9 + 16} = \sqrt{25} = 5$
 b) $\|(0, -3)\| = \sqrt{0^2 + (-3)^2} = \sqrt{0 + 9} = \sqrt{9} = 3$
 c) $\|(1, 1, 1)\| = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{1 + 1 + 1} = \sqrt{3}$
 d) $\|(3, 3)\| = \sqrt{3^2 + 3^2} = \sqrt{9 + 9} = \sqrt{2 * 9} = 3 * \sqrt{2}$
 e) $\|(-1, -1)\| = \sqrt{(-1)^2 + (-1)^2} = \sqrt{1 + 1} = \sqrt{2}$
 f) $\|(1, 2, 3)\| = \sqrt{1^2 + 2^2 + 3^2} = \sqrt{1 + 4 + 9} = \sqrt{14}$
 g) $\|(2, 0)\| = \sqrt{2^2 + 0^2} = \sqrt{4 + 0} = \sqrt{4} = 2$
 h) $\|(1, 2, 3, 4)\| = \sqrt{1^2 + 2^2 + 3^2 + 4^2} = \sqrt{1 + 4 + 9 + 16} = \sqrt{30}$
 i) $\|(3, 0, 0, 0)\| = \sqrt{3^2 + 0^2 + 0^2 + 0^2} = \sqrt{9 + 0 + 0 + 0} = \sqrt{9} = 3$

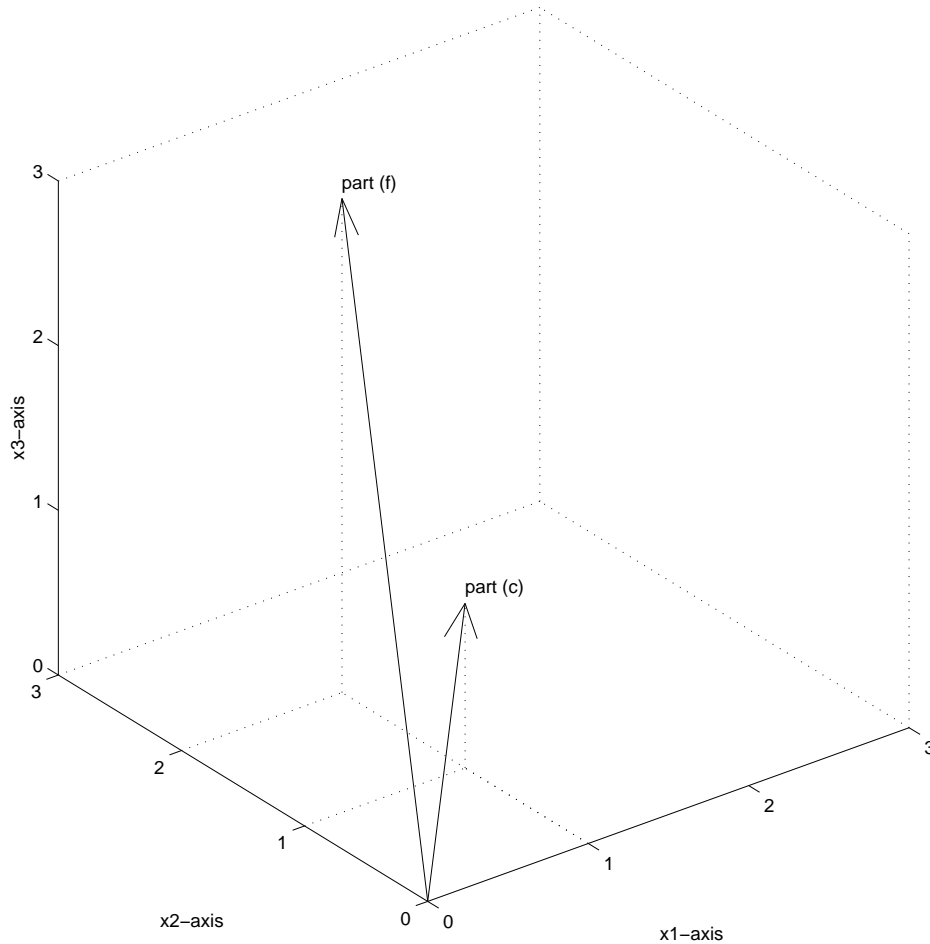
(3) Suppose you know that the angle between two vectors is as given below. What do you know about the sign of the inner product of the two vectors?

- a) 180
- b) 53
- c) 320
- d) 90

Ans: Recall that the sign of the inner product of two vectors v_1 and v_2 is given by the sign of the cosine of the angle between them.

- a) $\cos(180) = -1 \Rightarrow$ The sign of the inner product is negative.

FIGURE 2. The vectors for part 2c and 2f



- b) $\cos(53) > 0 \Rightarrow$ The sign of the inner product is positive.
 c) $\cos(320) > 0 \Rightarrow$ The sign of the inner product is positive.
 d) $\cos(90) = 0 \Rightarrow$ The sign of the inner product is zero as the vectors are perpendicular.

(4) Using the definition of linear independency, i.e.,

a set of vectors $\{v^1, \dots, v^k, \dots, v^m\}$ is a *linear independent set* if for all $\mathbf{t} \in \mathbb{R}^m$, $\sum_{k=1}^m t_k v^k = 0$ implies $\mathbf{t} = 0$, prove the following properties: (Note: once you have shown a property, you can use it to show the following ones)

- a) A singleton vector is a linear independent set *if and only if* it is not the zero vector.

Ans: First, let's prove the sufficiency condition by contrapositive ($(\text{not } B \Rightarrow \text{not } A) \Leftrightarrow (A \Rightarrow B)$). The nul vector is not a linear independent set, because we can find a $\lambda \neq 0$ such that $\lambda.v = 0$ (take $\lambda = 1$ for example). That proves that a singleton vector is a linear independent set then it is not equal to zero. For the necessary condition, let's take a non zero vector v , and let λ be a scalar such that $\lambda.v = 0$. Knowing that $v \neq 0$ there is at least one non zero component v_l of v . For this component, we can write $\lambda = 0/v_l$ so $\lambda = 0$ and v is a linear independent set.

- b) Two nonzero vectors are linearly independent *if and only if* they are not colinear (or proportional, i.e. for two vectors (u, v) , there exists $\lambda \in \mathbb{R}$ such that $u = \lambda.v$)

Ans: First, let's prove the sufficiency condition by contradiction. Let (u, v) be a couple of nonzero linearly independent vector that are colinear. By definition of colinearity, there exist a scalars α such that $v = \alpha.u$. Thus $v - \alpha.u = 0$, and this constitutes a linear combination of (u, v) equal to zero but with non zero scalars (at least the coefficient 1 in front of v is not equal to zero). Thus (u, v) is linear dependent which contradicts the assumption. Second, we prove the necessary part by contrapositive ($(\text{not } B \Rightarrow \text{not } A) \Leftrightarrow (A \Rightarrow B)$). Suppose that u and v are two linearly dependent non-zero vectors. Then we just need to show that they are colinear. By definition of linear dependence, there exist two scalars $(\alpha, \beta) \neq (0, 0)$ such that $\alpha.u + \beta.v = 0$. One of these scalars is necessarily different from zero, suppose it is α . Then, we can write $u = -\frac{\beta}{\alpha}.v$, so these two vectors are colinear. This proves that two vector that are not colinear are linearly independent .

- c) for $n > 1$, (v^1, \dots, v^n) is a linear dependent set *if and only if* one of the vector in the set v^i is a linear combination of the other $n - 1$ vectors.

Ans: The case of two vectors was shown in b). Now let's look at a case where $n > 2$. Suppose (v^1, \dots, v^n) are linearly dependent then there exist a set of scalars $(\lambda_1, \dots, \lambda_n)$ not all equal to

zero such that $\sum_{k=1}^n \lambda_k \cdot v^k = 0$. There is at least one scalar not equal to zero, suppose $\lambda_i \neq 0$ then we have $\lambda_i \cdot v^i = -\sum_{k \neq i} \lambda_k \cdot v^k$ or $v^i = -\frac{1}{\lambda_i} \sum_{k \neq i} \lambda_k \cdot v^k$ so v^i is a linear combination of the others $n - 1$ vectors with coefficients $\mu_k = -\frac{\lambda_k}{\lambda_i}$. This shows the sufficiency part.

Conversely, if there exists $i \in \llbracket 0, n \rrbracket$ such that v^i is a linear combination of the $n - 1$ other vectors, there exists a set of scalars $(\mu_1, \dots, \mu_{i-1}, \mu_{i+1}, \dots, \mu_n)$ such that $v^i = \sum_{k \neq i} \mu_k \cdot v^k$. We will construct a set of scalars in order to prove that these vectors are linearly dependent: set $\lambda_k = \mu_k$ for $k \neq i$ and $\lambda_i = -1$.

Then we have that $\sum_{k \neq i} \mu_k \cdot v^k - v^i = 0$, i.e. $\sum_{k \neq i} \lambda_k \cdot v^k + \lambda_i v^i = 0$, which simplifies to $\sum_{k=1}^n \lambda_k \cdot v^k = 0$. So we found a linear combination of the vectors equal to zero for which at least one scalar $\lambda_i = -1$ is not equal zero, so the vectors are linearly dependent.

d) If (v^1, \dots, v^n) is a linear independent set, and y is a different vector, (v^1, \dots, v^n, y) is linearly dependent *if and only if* y is a linear combination of v^1, \dots, v^n

Ans: First we look at the sufficiency case. Suppose (v^1, \dots, v^n) is a linear independent set, and (v^1, \dots, v^n, y) is linearly dependent. Because of this linear dependence, there exists a set of scalars $(\lambda_1, \dots, \lambda_{n+1})$ not all equal to 0 such that $\sum_{k=1}^n \lambda_k \cdot v^k + \lambda_{n+1} y = 0$. There are two possibilities: $\lambda_{n+1} y = 0$ or $\lambda_{n+1} y \neq 0$.

- If $\lambda_{n+1} = 0$ then $\sum_{k=1}^n \lambda_k \cdot v^k = 0$ and by linear independence all the scalars are equal to zero which is impossible by definition of the linear dependence of (v^1, \dots, v^n, y) . Thus $\lambda_{n+1} \neq 0$. Knowing that, we can write that $\sum_{k=1}^n \lambda_k \cdot v^k = -\lambda_{n+1} y$ and $y = -\frac{1}{\lambda_{n+1}} \sum_{k=1}^n \lambda_k \cdot v^k$. Thus y is a linear combination of the n vectors with coefficients $-\frac{\lambda_k}{\lambda_{n+1}}$.

For the necessary part, suppose that y is a linear combination of (v^1, \dots, v^n) , then there exists a set of scalars (μ_1, \dots, μ_n) such that $y = \sum_{k=1}^n \mu_k \cdot v^k$. By a similar reasoning as in our proof of c) we can construct a set of scalars $\lambda_1, \dots, \lambda_{n+1}$ not equal to zero such that $\sum_{k=1}^n \lambda_k \cdot v^k + \lambda_{n+1} y = 0$. We just need to define these scalars: set $\lambda_k = \mu_k$ for all $k \in \llbracket 1, n \rrbracket$ and set $\lambda_{n+1} = -1$. Thus we just showed that (v^1, \dots, v^n, y) is linearly dependent.

e) If (v^1, \dots, v^n) is a linear independent set, then any subset of this set (such as v^1, \dots, v^i , with $i < n$) is also linear independent.

Ans: This case only requires to show one sufficiency condition, I will proceed by contradiction. Suppose that (v^1, \dots, v^n) is linearly independent but that (v^1, \dots, v^i) is linearly dependent. Then there exists a set of scalars $(\lambda_1, \dots, \lambda_i)$ not all equal to zero such that $\sum_{k=1}^i \lambda_k \cdot v^k = 0$. We can add zero to this expression, so for $k \in \{i+1, \dots, n\}$ set $\lambda_k = 0$ then we have: $\sum_{k=1}^i \lambda_k \cdot v^k + \sum_{k=i+1}^n \lambda_k \cdot v^k = 0$, i.e., $\sum_{k=1}^n \lambda_k \cdot v^k = 0$. But at least one of the scalars $\{\lambda_1, \dots, \lambda_i\}$ is not equal to zero because $\Lambda \neq \mathbf{0}$. This contradicts our assumption of linear independence of (v^1, \dots, v^n) so necessarily (v^1, \dots, v^i) is linearly independent. This is true for any subset of the original set of linear independent vectors.

(5) Show that if \mathbf{v}^1 and \mathbf{v}^2 are linearly independent vectors in \mathbb{R}^2 , then any vector $\mathbf{w} \in \mathbb{R}^2$ can be written as a linear combination of \mathbf{v}^1 and \mathbf{v}^2 . To show this, use *only* the fact that \mathbf{v}^1 and \mathbf{v}^2 are linear independent iff they are not colinear. (i.e., do not use properties of matrices or determinants.)

Hint #1: Try to write \mathbf{w} as $\alpha\mathbf{v}^1 + \beta\mathbf{v}^2$. Under what conditions can you solve for α and β ?

Hint #2: one way of utilizing hint #1 is to use the following rather clumsy characterization of colinearity:

$$\mathbf{v}^1 \text{ and } \mathbf{v}^2 \text{ are colinear iff } \left\{ \begin{array}{l} \text{neither } v_1^1 \text{ nor } v_1^2 \text{ is zero} \implies \frac{v_2^1}{v_1^1} = \frac{v_2^2}{v_1^2} \quad \text{or} \\ \text{neither } v_2^1 \text{ nor } v_2^2 \text{ is zero} \implies \frac{v_1^1}{v_2^1} = \frac{v_1^2}{v_2^2} \quad \text{or} \\ \text{at least one of the vectors is zero} \end{array} \right. \quad (1)$$

The second and third branches of this characterization say, respectively, that either “rise over run” or “run over rise” must be the same for the two vectors.

Ans: Following hint #1, we will write

$$w_1 = \alpha v_1^1 + \beta v_1^2 \quad (2a)$$

$$w_2 = \alpha v_2^1 + \beta v_2^2 \quad (2b)$$

and will attempt to solve for α and β . We'll start with the “if” part, i.e., assume linear independence and show that we can solve for α and β . Since \mathbf{v}^1 and \mathbf{v}^2 are linearly independent and hence not colinear, either (a) $v_1^1 \neq 0$ or (b) $v_2^1 \neq 0$ (i.e., \mathbf{v}^1 cannot be zero). Without loss of generality, assume that (a) is true. (If (b) is true, flip the coefficients.) We can then divide both sides of (2a) by v_1^1 and obtain

$$\alpha = \frac{w_1}{v_1^1} - \beta \frac{v_1^2}{v_1^1} \quad (3)$$

now, substituting for α in (2a)

$$w_2 = \left(\frac{w_1}{v_1^1} - \beta \frac{v_1^2}{v_1^1} \right) v_2^1 + \beta v_2^2$$

so that

$$w_2 v_1^1 = w_1 v_2^1 + \beta (v_2^2 v_1^1 - v_1^2 v_2^1) \quad (4)$$

We can now solve for β iff $(v_1^2 v_2^1 - v_2^2 v_1^1) \neq 0$, in which case

$$\beta = \frac{w_2 v_1^1 - w_1 v_2^1}{v_2^2 v_1^1 - v_1^2 v_2^1}$$

and so, substituting this expression for β back into (3)

$$\begin{aligned} \alpha &= \frac{w_1}{v_1^1} - \beta \frac{v_1^2}{v_1^1} \\ &= \frac{w_1}{v_1^1} - \left(\frac{w_2 v_1^1 - w_1 v_2^1}{v_2^2 v_1^1 - v_1^2 v_2^1} \right) \frac{v_1^2}{v_1^1} \\ &= \frac{w_1 (v_2^2 v_1^1 - v_1^2 v_2^1) - v_1^2 (w_2 v_1^1 - w_1 v_2^1)}{v_1^1 (v_2^2 v_1^1 - v_1^2 v_2^1)} \\ &= \frac{w_1 v_2^2 - v_1^2 w_2}{v_2^2 v_1^1 - v_1^2 v_2^1}. \end{aligned}$$

We now need to show that \mathbf{v}^1 and \mathbf{v}^2 being linearly independent implies $(v_1^2 v_2^1 - v_2^2 v_1^1) \neq 0$. First note that if $v_1^2 = 0$, then necessarily $v_2^2 \neq 0$ and hence $(v_1^2 v_2^1 - v_2^2 v_1^1) = v_2^2 v_1^1 \neq 0$. On the other hand, if $v_1^2 \neq 0$ then $(v_1^2 v_2^1 - v_2^2 v_1^1) = v_1^1 v_1^2 \left(\frac{v_2^1}{v_1^1} - \frac{v_2^2}{v_1^1} \right)$. Now $v_1^1 v_1^2$ is non-zero by assumption, and we obtain that the term in parentheses is non-zero by negating the implication in the second branch of our characterization of colinearity.

Now for the “only if” part. Assume that \mathbf{v}^1 and \mathbf{v}^2 are linearly dependent. We need to show that we can't solve for α and β . From β , this will be the case if $(v_2^2 v_1^1 - v_1^2 v_2^1) = 0$. From (1), there are three possibilities:

- (a) for $i = 1, 2$, $v_1^i = v_2^i = 0$,
- (b) both v_1^1 and v_1^2 are nonzero and $\frac{v_2^1}{v_1^1} = \frac{v_2^2}{v_1^1}$.
- (c) both v_2^1 and v_2^2 are nonzero and $\frac{v_1^1}{v_2^1} = \frac{v_1^2}{v_2^2}$.

All three conditions imply that $(v_2^2 v_1^1 - v_1^2 v_2^1) = 0$.